

(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 9, September 2016

Area and Power Efficient Booth's Multipliers Based on Non Redundant Radix-4 Signed-Digit Encoding

S.Reshma¹, K.Rjendra Prasad²

P.G Student, Department of Electronics and Communication Engineering, Mallareddy Engineering College

Hyderabad, Telangana, India

Assistant Professor, Department of Electronics and Communication Engineering, Mallareddy Engineering College

Hyderabad, Telangana, India

ABSTRACT: In this paper, we introduce an architecture of pre-encoded multipliers for Digital Signal Processing applications based on off-line encoding of coefficients. To this extend, the Non-Redundant radix-4 Signed-Digit (NR4SD) encoding technique, which uses the digit values $\{-1, 0, +1, +2\}$ or $\{-2, -1, 0, +1\}$, is proposed leading to a multiplier design with less complex partial products implementation. Extensive experimental analysis verifies that the proposed pre-encoded NR4SD multipliers, including the coefficients memory, are more area and power efficient than the conventional Modified Booth scheme.

KEYWORDS: Multiplying circuits, Modified Booth encoding, Pre-Encoded multipliers, VLSI implementation.

I. INTRODUCTION

MULTIMEDIA and Digital Signal Processing (DSP) applications (e.g., Fast Fourier Transform (FFT), audio/video CoDecs) carry out a large number of multiplications with coefficients that do not change during the execution of the application. Since the multiplier is a basic component for implementing computationally intensive applications, its architecture seriously affects their performance.

Constant coefficients can be encoded to contain the least non-zero digits using the Canonic Signed Digit (CSD) representation [1]. CSD multipliers comprise the fewest non-zero partial products, which in turn decreases their switching activity. However, the CSD encoding involves serious limitations. Folding technique [2], which reduces silicon area by time multiplexing many operations into single functional

units, e.g., adders, multipliers, is not feasible as the CSD-based multipliers are hard-wired to specific coefficients. In [3], a CSD-based programmable multiplier design was proposed for groups of pre-determined coefficients that share certain features. The size of ROM used to store the groups of coefficients is significantly reduced as well as the area and power consumption of the circuit. However, this multiplier design lacks flexibility since the partial products generation unit is designed specifically for a group of coefficients and cannot be reused for another group. Also, this method cannot be easily extended to large groups of pre-determined coefficients attaining at the same time high efficiency.

Modified Booth (MB) encoding tackles the aforementioned limitations and reduces to half the number of partial products resulting to reduced area, critical delay and power consumption. However, a dedicated encoding circuit is required and the partial products generation is more complex. Kim et al. proposed a technique similar to [3], for designing efficient MB multipliers for groups of pre-determined coefficients with the same limitations described in the previous paragraph.

II. MODIFIED BOOTH ALGORITHM

The proposed NR4SD encoding scheme uses one of the following sets of digit values: $\{-1, 0, +1, +2\}$ or $\{-2, -1, 0, +1\}$,. In order to cover the dynamic range of the 2's complement form, all digits of the proposed representation are encoded according to NR4SD except the most significant one that is MB encoded. Using the proposed encoding formula, we pre-encode the standard coefficients and store them into a ROM in a condensed form (i.e., 2 bits per digit). Compared



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 9, September 2016

to the pre-encoded MB multiplier in which the encoded coefficients need 3 bits per digit, the proposed NR4SD scheme reduces the memory size. Also, compared to the MB form, which uses five digit values{-2,-1,0,+1,+2}, proposed NR4SD encoding uses four digit values. Thus, the NR4SD-based pre-encoded multipliers include a less complex partial products generation circuit. We explore the efficiency of the aforementioned pre-encoded multipliers taking into account the size of the coefficients' ROM.

Modified Booth (MB) is a redundant radix-4 encoding technique [6], [7]. Considering the multiplication of the 2's complement numbers A, B, each one consisting of n=2k bits, B can be represented in MB form as

$$B = \langle b_{n-1} \dots b_0 \rangle_{2's} = -b_{2k-1} 2^{2k-1} + \sum_{i=0}^{2k-2} b_i 2^i$$
$$= \langle \mathbf{b}_{k-1}^{MB} \dots \mathbf{b}_0^{MB} \rangle_{MB} = \sum_{j=0}^{k-1} \mathbf{b}_j^{MB} 2^{2j}.$$
(1)

$$\mathbf{b}_{j}^{MB} = -2b_{2j+1} + b_{2j} + b_{2j-1},$$
-(2)

where b-1 = 0. Each MB digit is represented by the bits s, one and two (Table 1). The bit s shows if the digit is negative (s=1) or positive (s=0). One shows if the absolute value of a digit equals 1 (one=1) or not (one=0). Two shows if the absolute value of a digit equals 2 (two=1) or not (two=0). Using these bits, we calculate the MB digits MB bj as follows:

$$\mathbf{b}_j^{MB} = (-1)^{s_j} \cdot (one_j + 2two_j).$$
-(3)

Equation (4) from the mb encoding signals

$$s_j = b_{2j+1}, \quad one_j = b_{2j-1} \oplus b_{2j},$$
$$two_j = (b_{2j+1} \oplus b_{2j}) \wedge \overline{one_j}.$$
-(4)

b_{2j+1}	b_{2j}	b_{2j-1}	\mathbf{b}_{j}^{MB}	s_j	one_j	two_j
0	0	0	0	0	0	0
0	0	1	+1	0	1	0
0	1	0	+1	0	1	0
0	1	1	+2	0	0	1
1	0	0	-2	1	0	1
1	0	1	-1	1	1	0
1	1	0	-1	1	1	0
1	1	1	0	1	0	0

Table 1.modified booth encoding table

III. NON REDUNDANT SIGNED DIGIT ENCODING

In this section, we present the Non-Redundant radix-4 Signed Digit (NR4SD) encoding technique. As in MB form, the number of partial products is reduced to half. When encoding the 2's complement number B, digits bNR- take one of four values: $\{-2,-1,0,+1\}$ at the NR4SD- and Bnr+ take one of four values $\{-1,0,+1,+2\}$ at the NR4SD+. algorithm, respectively. Only four different values are used and not five as in MB algorithm, which leads to 0 < j < k - 2. As we need to cover the dynamic range of the 2's complement form, the most significant digit is MB encoded (i.e., bMB $\{-2,-1,0,+1,+2\}$). The NR4SD- and NR4SD+ encoding algorithms are illustrated in detail in Fig. 1 and 2, respectively.



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 9, September 2016



Fig.1 Block Diagram of the NR4SD- Encoding Scheme at the (a) Digit and (b) Word Level.



Fig.2 Block Diagram of the NR4SD+ Encoding Scheme at the (a) Digit and (b) Word Level.

NRS4D- algorithm

Step 1: Consider the initial values j = 0 and c0=0.

Step 2: Calculate the carry c2j+1 and the sum n+ 2j of a Half Adder (HA) with inputs b2j and c2j (Fig. 1a). $c_{2j+1} = b_{2j} \wedge c_{2j}, \quad n_{2j}^{+} = b_{2j} \oplus c_{2j}.$

Step 3: Calculate the positively signed carry c2j+2 (+) and the negatively signed sum n 2j+1 (-) of a Half Adder* (HA*) with inputs b2j+1 (+) and c2j+1 (+) The outputs c2j+2 and n 2j+1 of the HA* relate to its inputs as follows

$$2c_{2j+2} - n_{2j+1}^- = b_{2j+1} + c_{2j+1}.$$

Step 4: Calculate the value of the bNR j digit.

$$\mathbf{b}_{j}^{NR-} = -2n_{2j+1}^{-} + n_{2j}^{+}.$$

Equation (5) results from the fact that n2j+1 is negatively signed and n2j+1 is positively signed. Step 5: j := j + 1.

Step 6: If $(j < k \square 1)$, go to Step 2. If $(j = k \square 1)$, encode the most significant digit based on the MB algorithm and considering the three consecutive bits to be b2k-1, b2k-2 and c2k-2 (Fig. 1b). If (j = k), stop.

-(5)

Table 2 shows how the NR4SD- digits are formed. Equations (6) show how the NR4SD- encoding signals.

2's complement		NR49	SD ⁻ form Dig			git NR4SD- Enco		ncoding	
b_{2j+1}	b_{2j}	c_{2j}	c_{2j+2}	n_{2j+1}^{-}	n_{2j}^+	b_j^{NR-}	one_j^+	one_j^-	two_j^-
0	0	0	0	0	0	0	0	0	0
0	0	1	0	0	1	+1	1	0	0
0	1	0	0	0	1	+1	1	0	0
0	1	1	1	1	0	-2	0	0	1
1	0	0	1	1	0	-2	0	0	1
1	0	1	1	1	1	-1	0	1	0
1	1	0	1	1	1	-1	0	1	0
1	1	1	1	0	0	0	0	0	0

table.2 NRS4D- encoding.



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 9, September 2016

$$one_{j}^{+} = \overline{n_{2j+1}^{-}} \wedge n_{2j}^{+},$$

$$one_{j}^{-} = \overline{n_{2j+1}^{-}} \wedge n_{2j}^{+},$$

$$two_{j}^{-} = \overline{n_{2j+1}^{-}} \wedge \overline{n_{2j}^{+}}.$$
(6)

We observe that the NR4SD \square form has larger dynamic range than the 2's complement form. NRS4D+ encoding

Step 1: Consider the initial values j = 0 and c0=0.

Step 2: Calculate the carry c2j+1 and the sum n+ 2j of a Half Adder (HA) with inputs b2j and c2j (Fig. 2a).

$$2c_{2j+1} - n_{2j}^{-} = b_{2j} + c_{2j}$$

Step 3: Calculate the positively signed carry c2j+2 (+) and the negatively signed sum n 2j+1 (-) of a Half Adder* (HA*) with inputs b2j+1 (+) and c2j+1 (+)

The outputs c2j+2 and n 2j+1 of the HA* relate to its inputs as follows

$$c_{2j+1} = b_{2j} \lor c_{2j}, \quad n_{2j}^- = b_{2j} \oplus c_{2j}.$$

Step 4: Calculate the value of the bNR j digit.

$$\mathbf{b}_{j}^{NR+} = 2n_{2j+1}^{+} - n_{2j}^{-}.$$

Equation (7) results from the fact that n2j+1 is negatively

signed and n2j+ is positively signed.

Step 5: j := j + 1.

Step 6: If $(j < k \square 1)$, go to Step 2. If $(j = k \square 1)$, encode the most significant digit based on the MB algorithm and considering the three consecutive bits to be b2k-1, b2k-2 and c2k-2 (Fig. 1b). If (j = k), stop.

-(7)

Table 3 shows how the NR4SD+ digits are formed. Equations (8) show how the NR4SD+ encoding signals.

2's complement		NR45	SD^+ for	m	Digit	NR4SD ⁺ Encoding			
b_{2j+1}	b_{2j}	c_{2j}	c_{2j+2}	n_{2j+1}^+	n_{2j}	\mathbf{b}_{j}^{NR+}	one_j^+	one_j^-	two_j^+
0	0	0	0	0	0	0	0	0	0
0	0	1	0	1	1	+1	1	0	0
0	1	0	0	1	1	+1	1	0	0
0	1	1	0	1	0	+2	0	0	1
1	0	0	0	1	0	+2	0	0	1
1	0	1	1	0	1	-1	0	1	0
1	1	0	1	0	1	-1	0	1	0
1	1	1	1	0	0	0	0	0	0

Table.3 NR4SD+ encoding

As observed in the NR4SD- encoding technique, the NR4SD+ form has larger dynamic range than the 2's complement form.

Considering the 8-bit 2's complement number N, Table 4 exposes the limit values and two typical values of N, and presents the MB, NR4SD- and NR4SD+ digits that result when applying the corresponding encoding techniques to each value of N we considered. We added a bar above the negatively signed digits in order to distinguish them from the positively signed ones.

2's Complement	10000000	10011010	01011001	01111111
Integer	-128	-102	+89	+127
Modified Booth	$\bar{2} \ 0 \ 0 \ 0$	$\overline{2}$ 2 $\overline{1}$ $\overline{2}$	$1 2 \overline{2} 1$	2001
NR4SD ⁻	$\bar{2} \ 0 \ 0 \ 0$	$\overline{1} \ \overline{2} \ \overline{1} \ \overline{2}$	$2\ \bar{2}\ \bar{2}\ 1$	2001
NR4SD+	$\bar{2}$ 0 0 0	2122	1121	2001

Table.4 numerical examples of encoding techniques.



(An ISO 3297: 2007 Certified Organization)



Fig3.system architecture of mb multiplier.

IV. PRE-ENCODED MB MULTIPLIER DESIGN

In this section, we explore the implementation of pre-encoded multipliers. One of the two inputs of these multipliers is pre-encoded either in MB or in NR4SD \square / NR4SD+ representation. We consider that this input comes from a set of fixed coefficients (e.g. the coefficients for a number of filters in which this multiplier will be used in a dedicated system or

the sine table required in an FFT implementation). The coefficients are encoded off-line based on MB or NR4SD algorithms and the resulting bits of encoding are stored in a ROM. Since our purpose is to estimate the efficiency of the proposed multipliers, we first present a review of the conventional MB multiplier in order to compare it with the preencoded schemes.



Fig.4the ROM of Pre-Encoded multipliers with standard coefficients in MB form.

In the pre-encoded MB multiplier scheme, the coefficient B is encoded off-line according to the conventional MB form (Table 1). The resulting encoding signals of B are stored in a ROM. The circled part of Fig. 3, which contains the ROM with coefficients in 2's complement form and the MB encoding circuit, is now totally replaced by the ROM of Fig. 4. The MB encoding blocks of Fig. 3 are omitted. The new ROM of Fig. 5 is used to store the encoding signals of B and feed them into the partial product generators (PPj Generators - PPG) on each clock cycle. Targeting to decrease switching activity, the value '1' of sj in the last entry of Table 1 is replaced by '0'. The sign sj is now given by the relation

 $sj = b2j+1 (b2j+1 ^ b2j ^ b2j \square 1):$

As a result, the PPG of Fig. 4a is replaced by the one of Fig. 4b. Compared to (4), (12) leads to a more complex design. However, due to the pre-encoding technique, there is no area / delay overhead at the circuit. The partial products, properly weighted, and the correction term (COR) of (11) are fed into a CSA tree. The input carry cin;j of (11) is computed as cin;j = sj based on (12) and Table 1. The CS output of the tree is finally merged by a fast CLA adder. However, the ROM width is increased. Each digit requests three encoding bits (i.e., s, two and one (Table 1)) to be stored in the ROM. Since the n-bit coefficient B needs three bits per digit when encoded in MB form, the ROM width requirement is 3n/2 bits per coefficient. Thus, the width and the overall size of the ROM are increased by 50% compared to the ROM of the conventional scheme (Fig. 3).



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 9, September 2016



Fig.5generation of ppj for conventional and pre-encoded mb multiplier.



Fig.6generation of ppj for NR4SD- and NR4SD+ multiplier.

Pre-Encoded NR4SD Multipliers Design

The system architecture for the pre-encoded NR4SD multipliers is presented in Fig. 6. Two bits are now stored in ROM: n2j+1, n+2j (Table 2) for the NR4SD or n+2j+1, n2j (Table 3) for the NR4SD+ form. In this way, we reduce the memory requirement to n+1bits per coefficient while the corresponding memory required for the pre-encoded MB scheme is 3n/2 bits per coefficient. Thus, the amount of stored bits is equal to that of the conventional MB design, except for the most significant digit that needs an extra bit as it is MB encoded. Compared to the pre-encoded MB multiplier, where the MB encoding blocks are omitted, the pre-encoded NR4SD multipliers need extra hardware to generate the signals of (6) and (8) for the NR4SD- and NR4SD+ form, respectively. The NR4SD encoding blocks of Fig. 6 implement the circuitry of Fig. 7. Each partial product of the pre-encoded NR4SD- and NR4SD+ multipliers is implemented based on Fig. 4c and 4d, respectively, except for the PPk1 that corresponds to the most significant digit. As this digit is in MB form, we use the PPG of Fig. 4b applying the change mentioned in Section 4.2 for the sj bit. The partial products, properly weighted, and the correction term (COR) of (11) are fed into a CSA tree. The input carry cin;j of (11) is calculated as cin;j = twoj_one j and cin;j = onej for the NR4SD- and NR4SD+ pre-encoded multipliers, respectively, based on Tables 2 and 3. The carry-save output of the CSA tree is finally summed using a fast CLA added.



Fig.7 system architecture of NR4SD encoding.



Fig.8 Extra Circuit Needed in the NR4SD Multipliers to Complete the (a) NR4SD and (b) NR4SD+ Encoding.

V. IMPLEMENTATION RESULTS

We implemented in Verilog the multiplier designs of Table 4. The PPGs for the NR4SD-, NR4SD+ multipliers (Fig. 5) contain a large number of inverters since all the A bits are complemented in case of a negative digit. We used Xilinx's



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 9, September 2016

ise to synthesize the evaluated designs, considering the highest optimization degree and keeping the hierarchy of the designs.

	Design	Innut A	Inpi	Input B Encoding		
	Design	Input II	Type	Technique	width	
Conventional MB		ement	MB	MB encoding	<i>n</i> -bit	
ed	MB	mple 1-bit	MB	Fully Pre-Encoded	3n/2-bit	
Encod	NR4SD-	s co	NR4SD-	Partially	(n+1)-bit	
	NR4SD+	5,	NR4SD+	Pre-Encoded	(n+1)-bit	

Table 4.multiplier design

The below table 5 and table 6 are the synthasis results for the modified booth and non-redundant sign digit encoding minus and non redundant sign digit encoding plus for 16 and 32 bits respectively.

	Mb	NR4SD-	NR4SD
	encoding		+-
NUMBER	207	129	134
OF SLICES			
NUMBER	11	6	6
OF			
FLIPFLOPS			
4INPUT	364	222	230
LUTS			
NUMBER	54	54	54
OF IOBS			

Table 5.syntasis result comparison for 16 bit.

-	_		
	Mb encoding	NR4SD-	NR4
			SD+
NUMBER	783	431	393
OF SLICES			
NUMBER	13	8	9
OF			
FLIPFLOPS			
4INPUT	1402	754	689
LUTS			
NUMBER	102	102	102
OF IOBS			

Table 6 syntasis result and comparision for 32 bit.

me	Value	0 ns	100) ns	200 ns	300 ns	400 n:	i Tar far tar ta	500 ns
p [31:0]	25		5 🗙 119	X 322 X					-132
🗓 clk	0			nnn			nnhr		
🗓 rst	0								
addr[3:0]	0	0		<u>x</u> 2 <u>x</u>					3
a[15:0]	5		5 17	X 14 X					12

Fig.9 simulation result for modified booth encoding.

Name	Value	0 ns	100 ns	200 ns	300 ns 44
🕨 🔣 p[31:0]	238	0 100	300)		238
16 clk	1		տեսու		
🔚 rst	0				
🕨 📷 addr[3:0]	2	0			2
🗩 📑 a[15:0]	34	0 20	X 30 X		34

Fig 10 simulation result for NRS4D-encoding



(An ISO 3297: 2007 Certified Organization)

Vol. 5, Issue 9, September 2016

Fig9,fig10,fig11 shows the simulation result for multiplier based on modified booth encoding and non redundant signed digit encoding minus and non redundant signed digit encoding plus respectively.



Fig.11 simulation result for NRS4D+encoding.

VI. CONCLUSION

In this paper, new designs of pre-encoded multipliers are explored by off-line encoding the standard coefficients and storing them in system memory .We propose encoding these coefficients in the Non-Redundant radix-4 Signed-Digit (NR4SD) form .The proposed pre-encoded NR4SD multiplier designs are more area and power efficient compared to the conventional and pre-encoded MB designs. Extensive experimental analysis verifies the gains of the proposed preencoded NR4SD multipliers in terms of area complexity and power consumption compared to the conventional MB multiplier.

REFERENCES

[1] G. W. Reitwiesner, "Binary arithmetic," Advances in Computers, vol. 1, pp. 231-308, 1960.

[2] K. K. Parhi, VLSI Digital Signal Processing Systems: Design and Implementation. John Wiley & Sons, 2007.

[3] K. Yong-Eun, C. Kyung-Ju, J.-G. Chung, and X. Huang, "Csdbased programmable multiplier design for predetermined

coefficient groups," IEICE Trans. Fundam. Electron. Commun. Comput. Sci., vol. 93, no. 1, pp. 324–326, 2010. [4] O. Macsorley, "High-speed arithmetic in binary computers," Proc. IRE, vol. 49, no. 1, pp. 67–91, Jan. 1961.

[5] W.-C. Yeh and C.-W. Jen, "High-speed booth encoded parallel multiplier design," IEEE Trans. Comput., vol. 49, no. 7, pp. 692-701, Jul. 2000. [6] Z. Huang, "High-level optimization techniques for low-power multiplier design," Ph.D. dissertation, Department of Computer Science, University of California, Los Angeles, CA, 2003.

[7] Z. Huang and M. Ercegovac, "High-performance low-power left-to-right array multiplier design," IEEE Trans. Comput., vol. 54, no. 3, pp. 272-283, Mar. 2005.

[8] Y.-E. Kim, K.-J. Cho, and J.-G. Chung, "Low power small area modified booth multiplier design for predetermined coefficients," IEICE Trans. Fundam. Electron. Commun. Comput. Sci., vol. E90-A, no. 3, pp. 694-697, Mar. 2007.